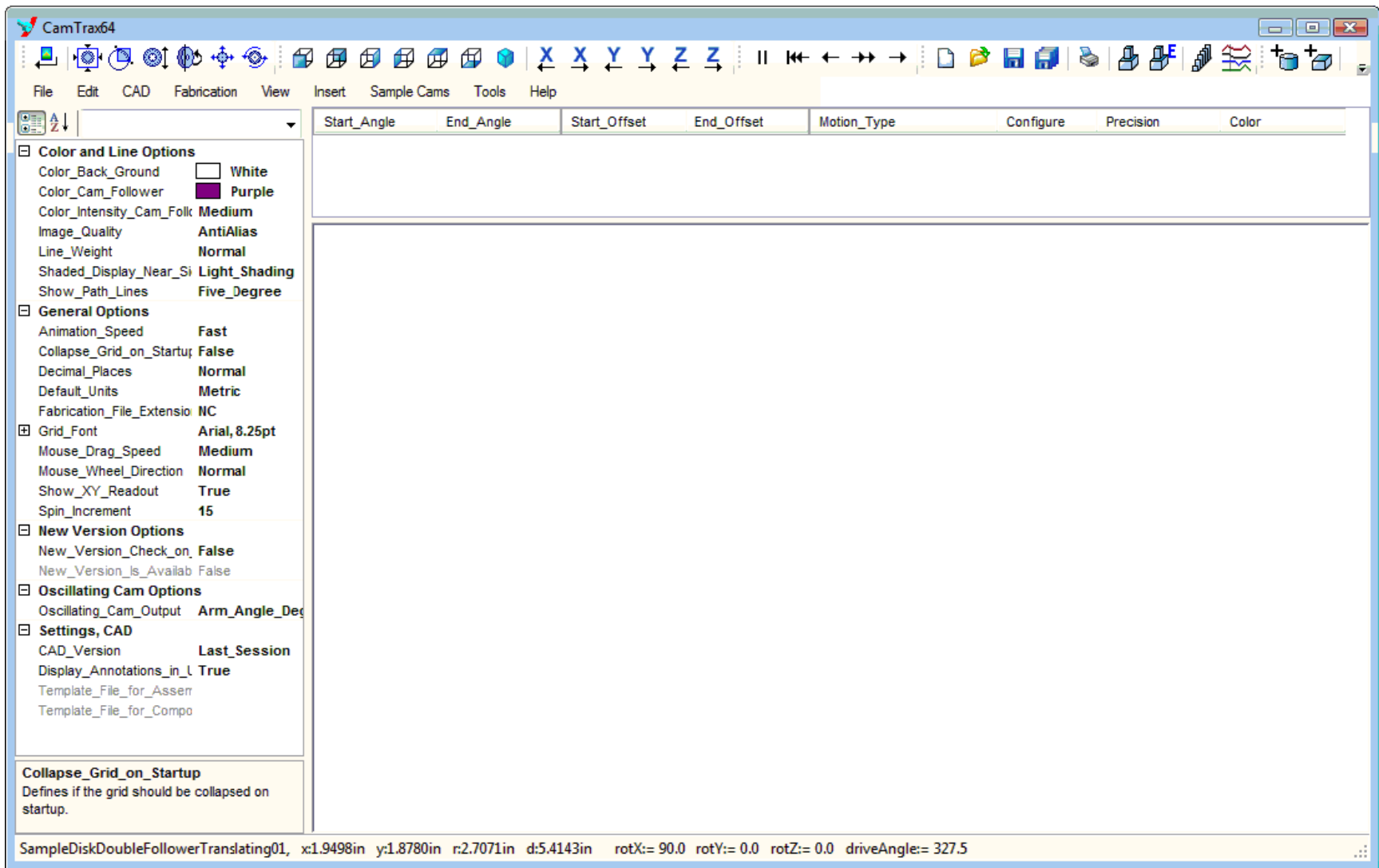
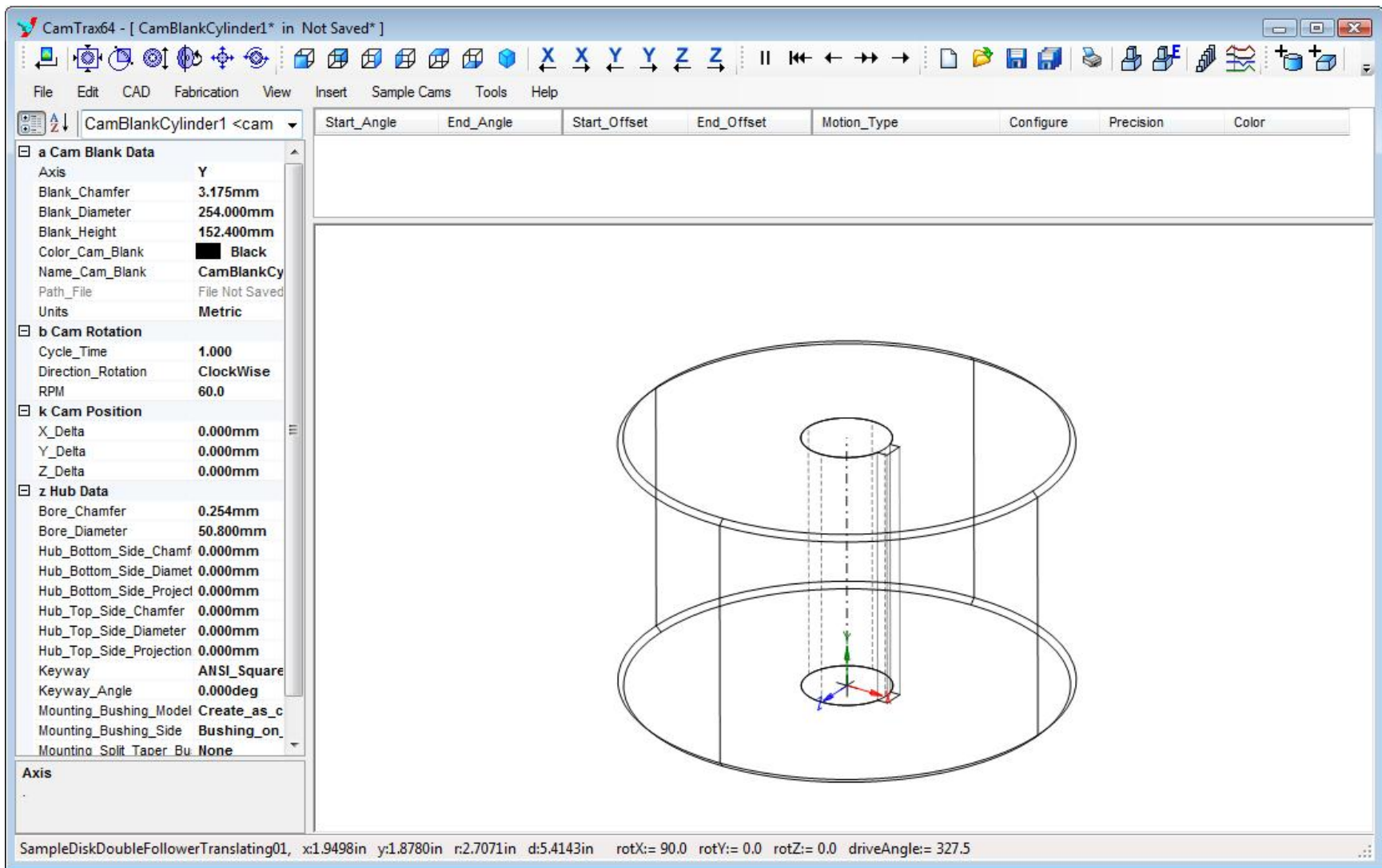
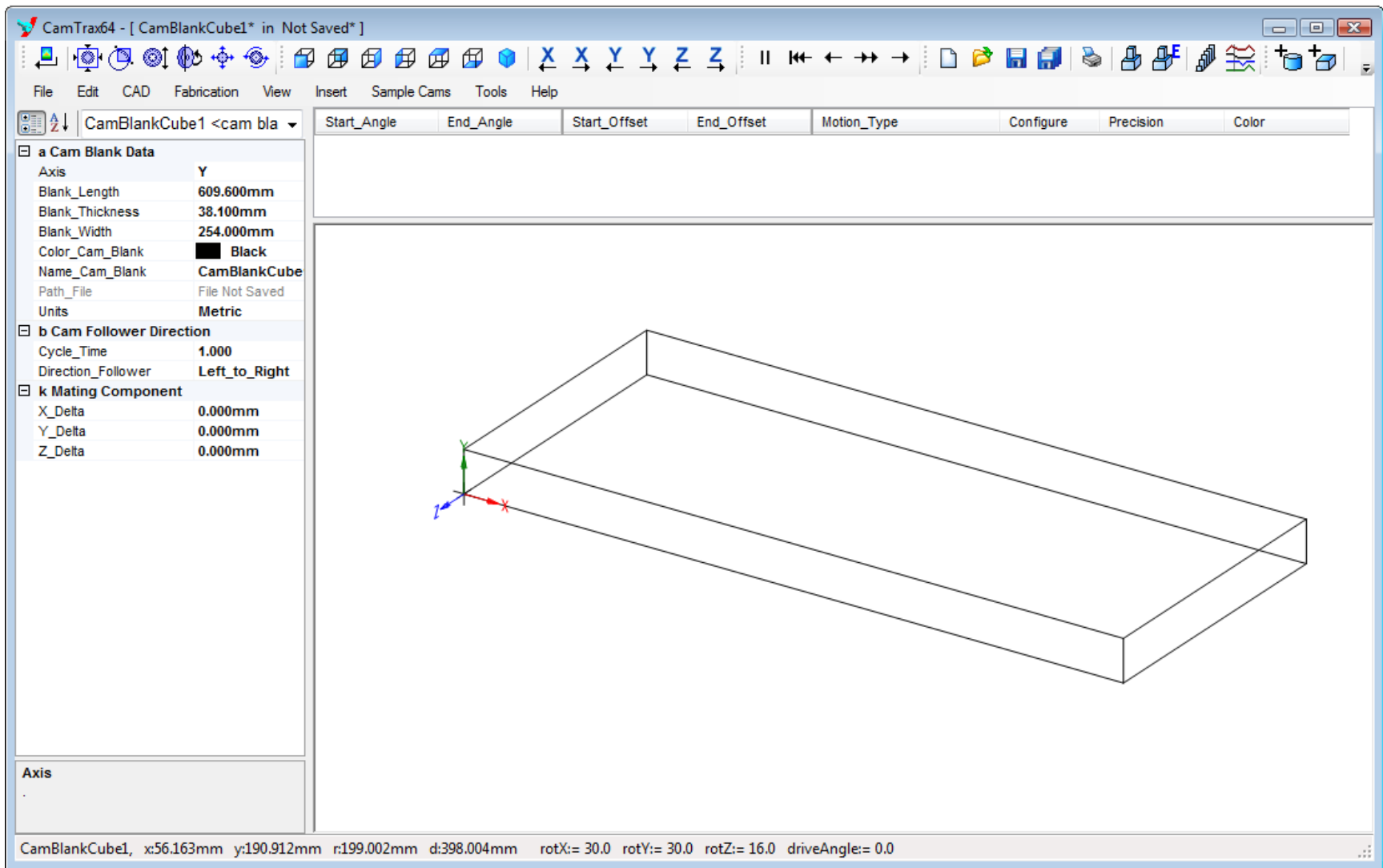




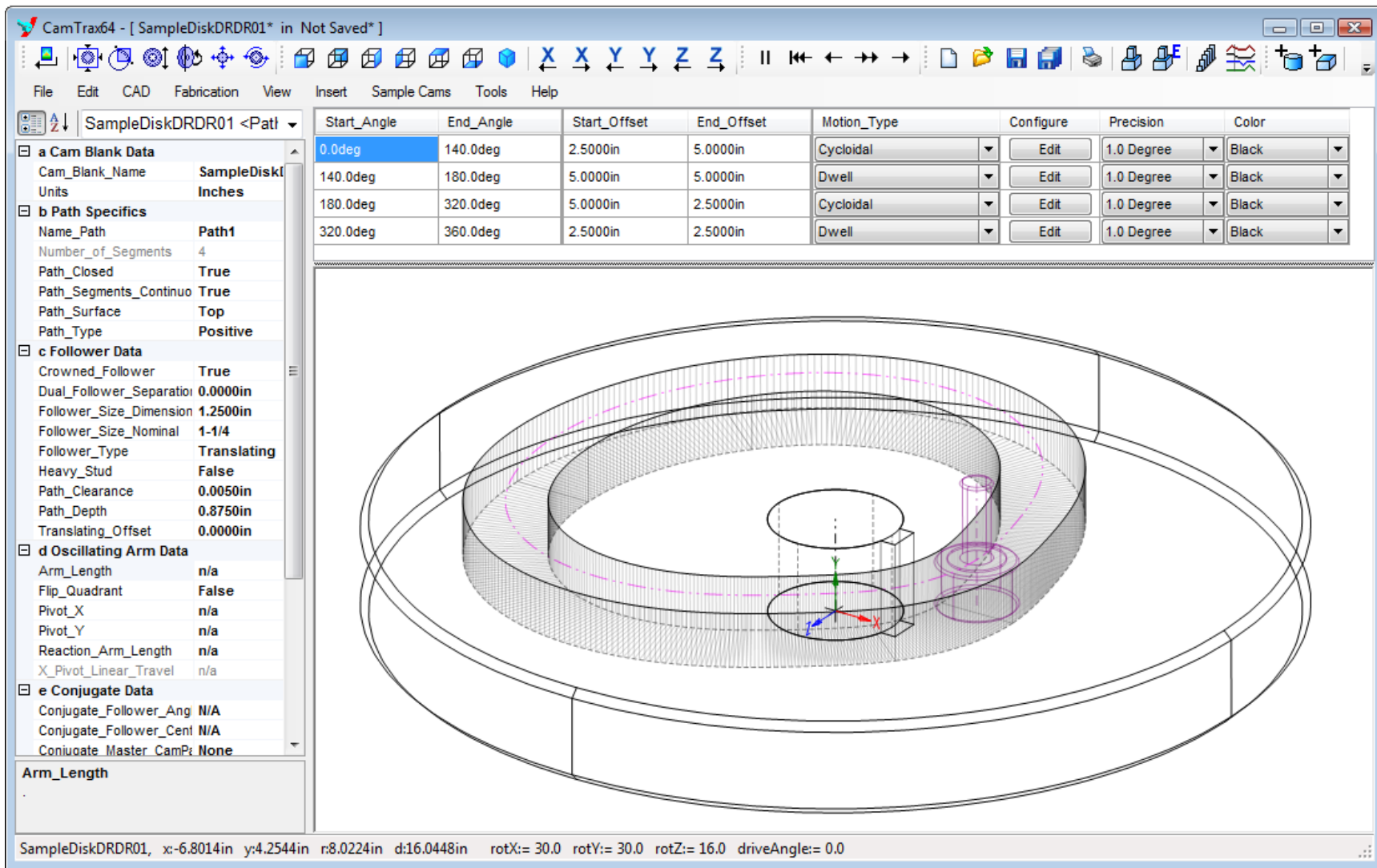
Options



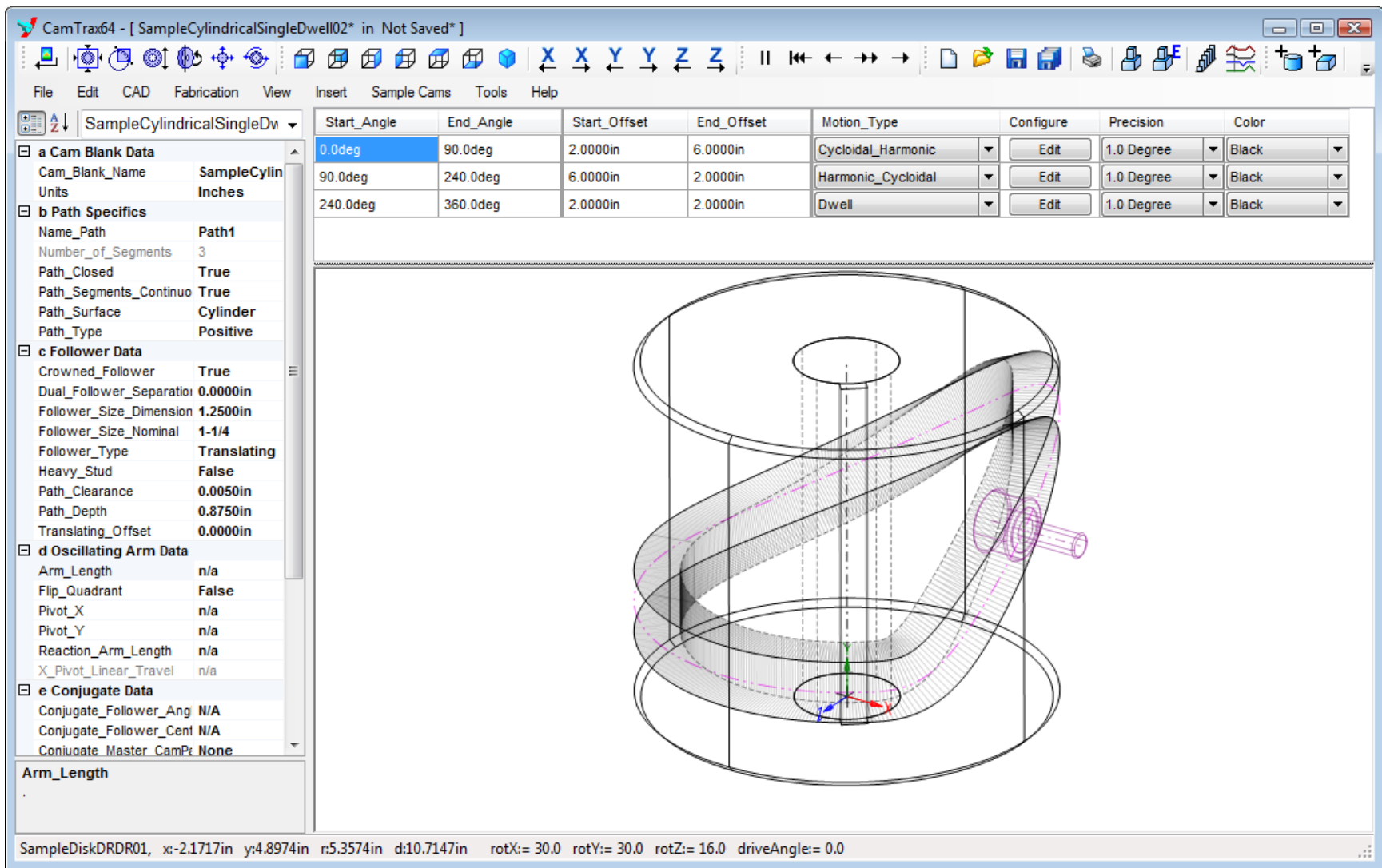
Cam Blank, Cylinder



Cam Blank, Cube



Dwell-Rise-Dwell-Return Sample Disk Cam



Single Dwell Cylindrical Cam

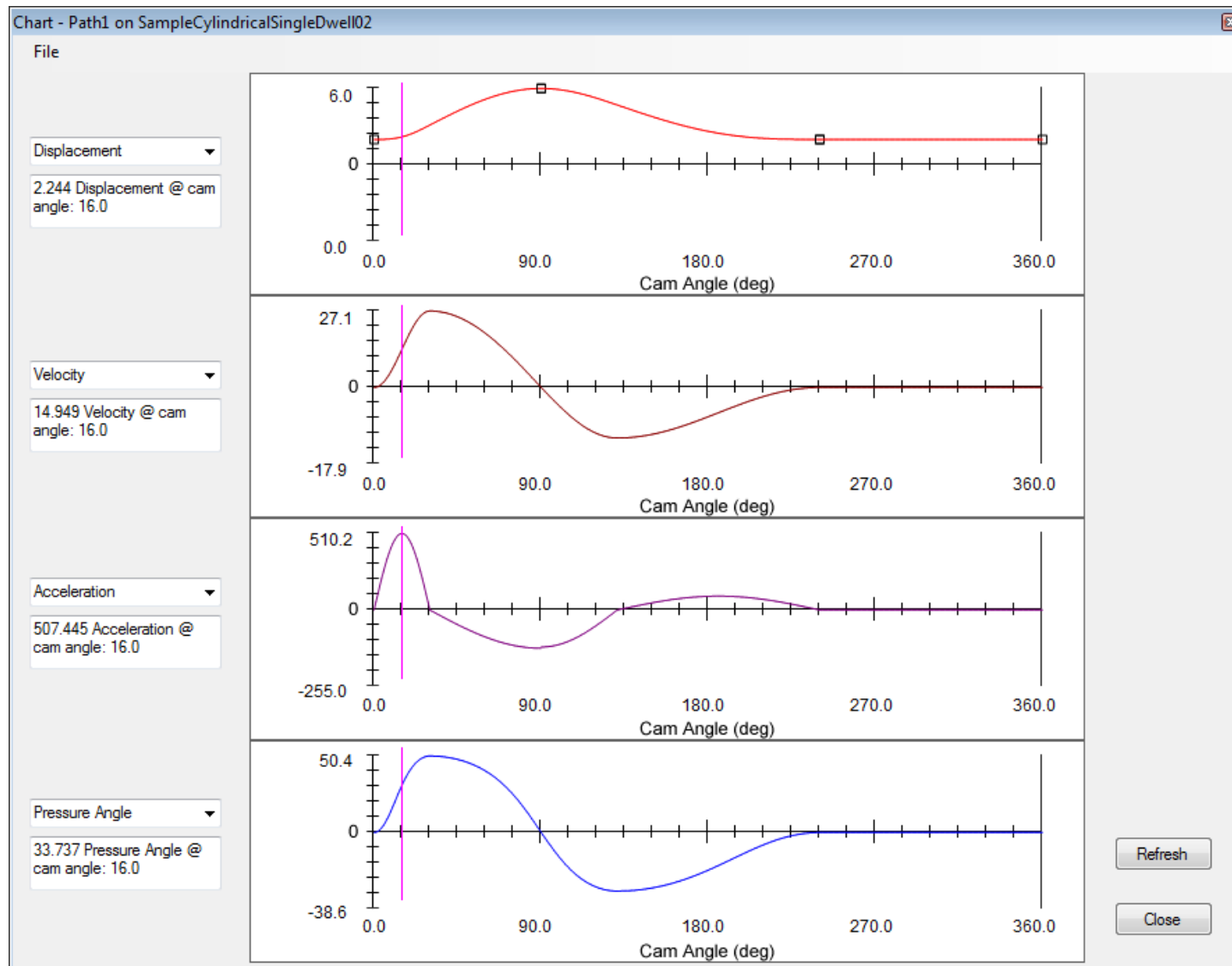
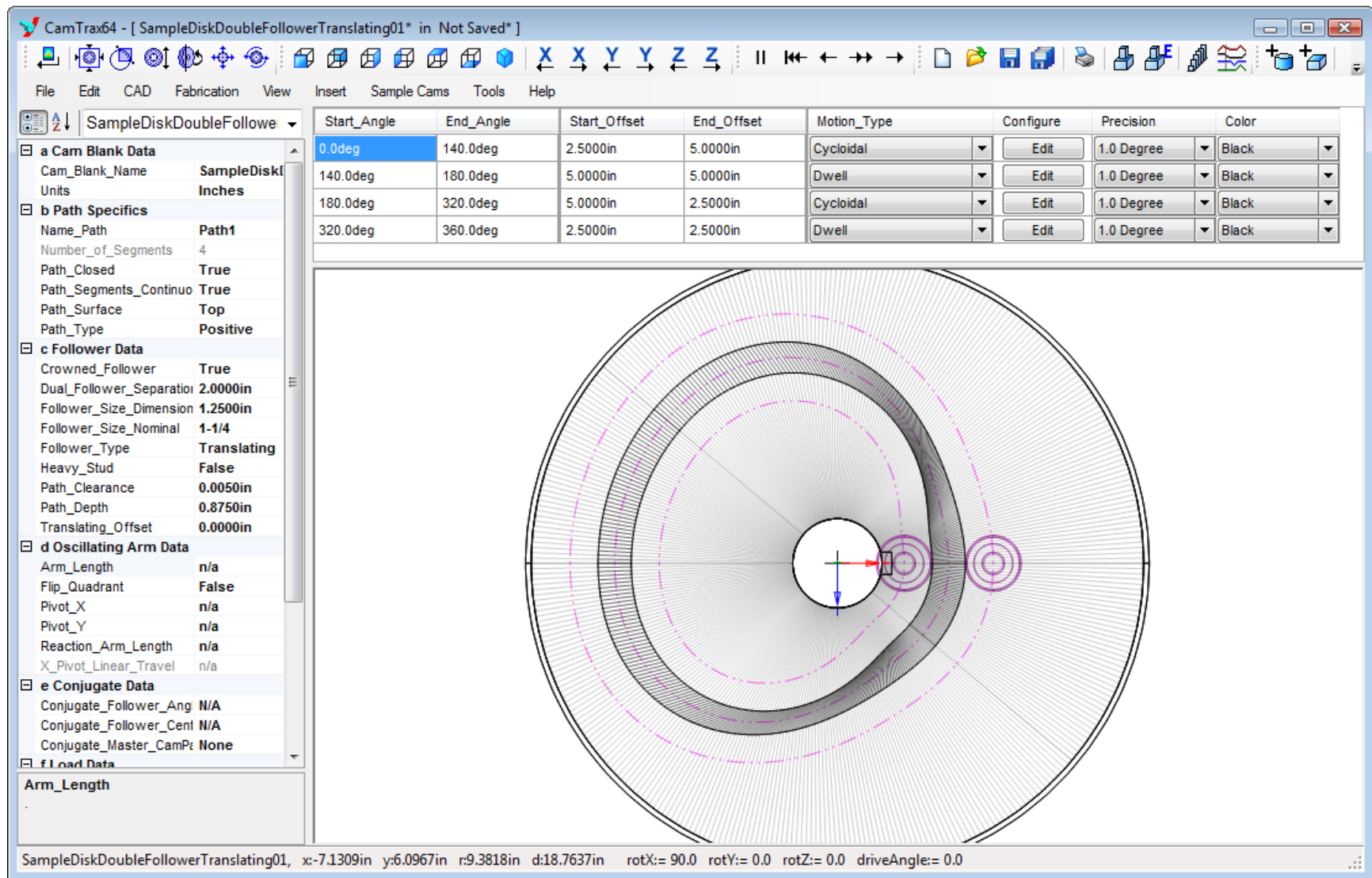
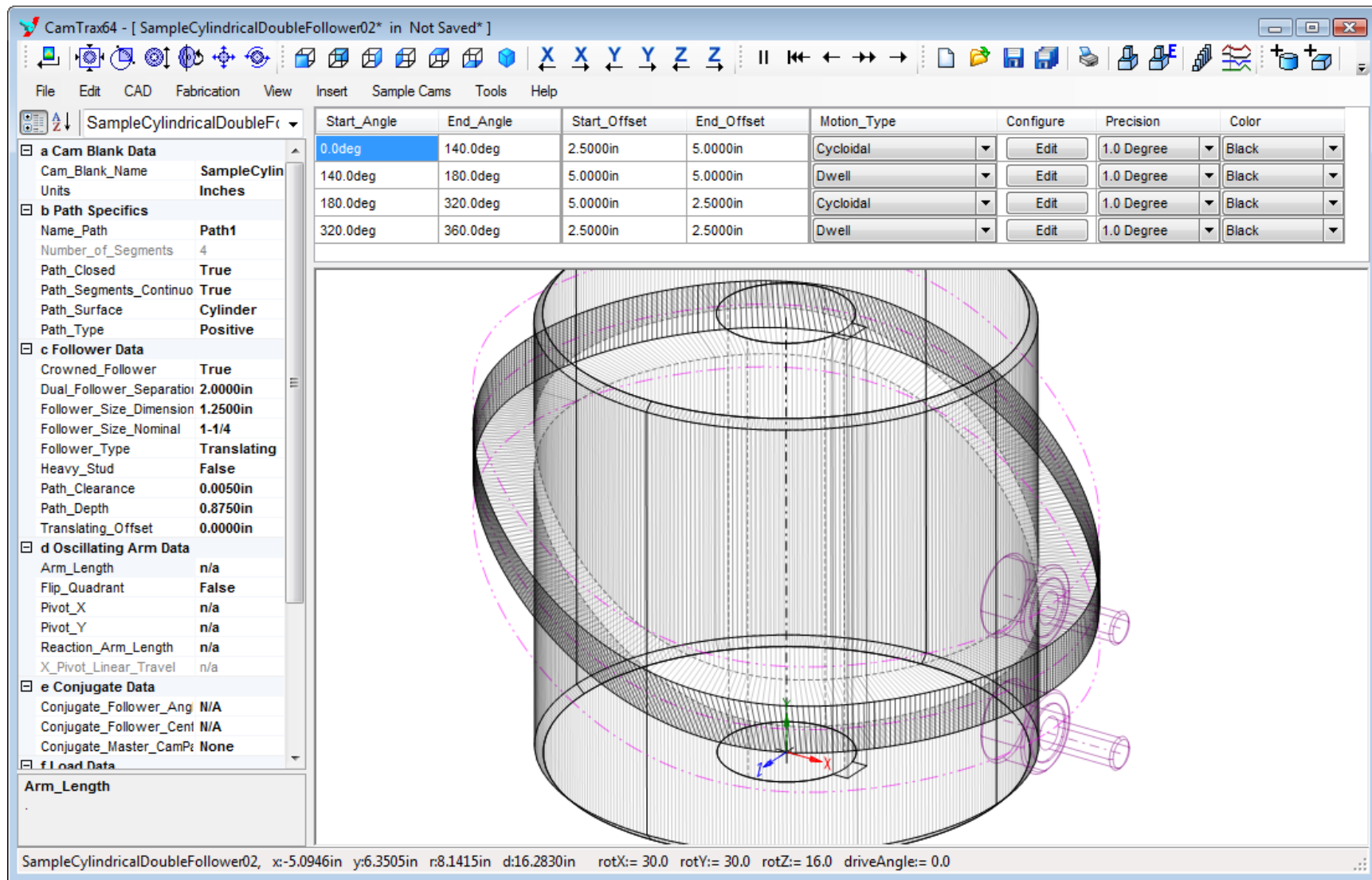


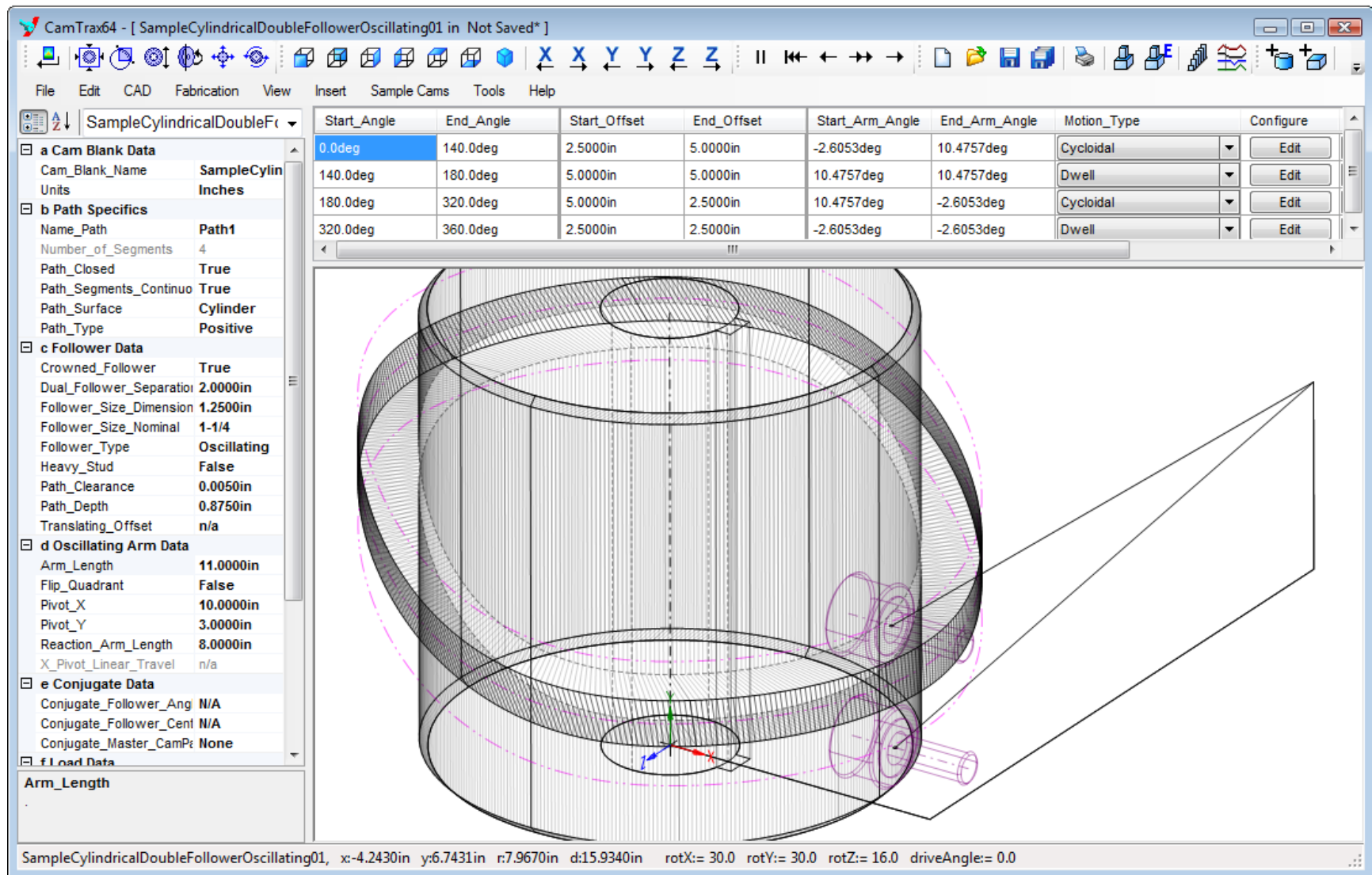
Chart of a Single Dwell Cam Path



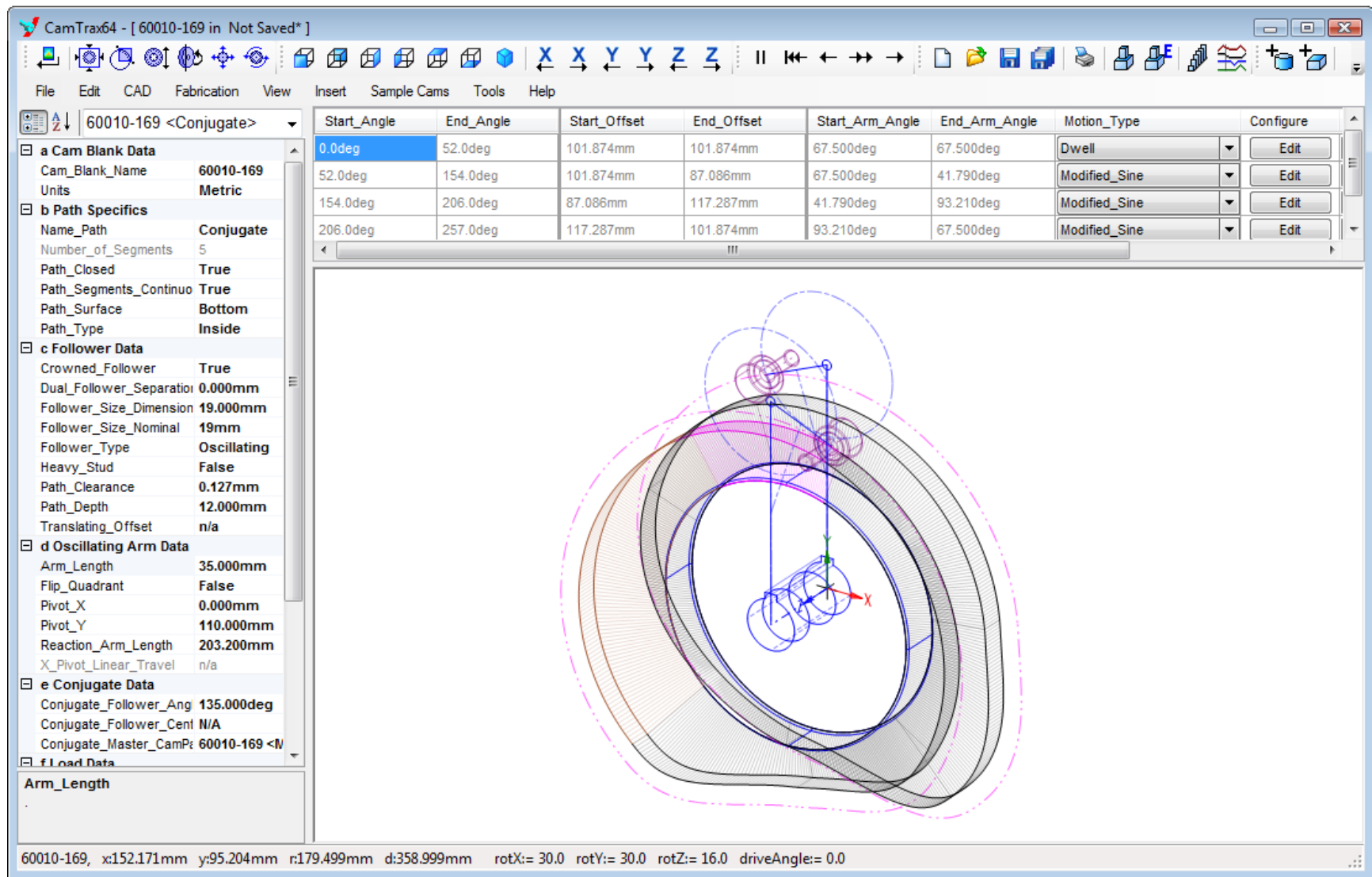
Top View of a Double Roller Disk Cam



Double Roller Cylindrical Cam



Oscillating Double Roller Cylindrical Cam



Oscillating Disk Cam with Master and Conjugate Paths

SampleDiskNoDwell02.txt - Notepad

File Edit Format View Help

File Location: Z:\SampleDiskNoDwell02.txt

Date: Thursday, May 28, 2009

Time: 7:54:38 AM

----- CamTrax64 -----

CAM DIRECTION: CLOCKWISE

PATH TYPE: POSITIVE

FOLLOWER DIAMETER: 1-1/4

FOLLOWER SPECIFICATION: TRANSLATING

PATH CLEARANCE: 0.0050in

PATH DEPTH: 0.8750in

CYCLE TIME (sec): 1

RPM: 60.0

FOLLOWER CONTACT WIDTH: 0.5000in

MODULUS OF ELASTICITY: 30x10^6

WEIGHT OF ACCELERATED ELEMENTS: 10.0lb

EXTERNAL FORCES: 0.0lb

SPRING RATING: 0.0000lb/in

SPRING COMPRESSION START AT: 0.2500in

SPRING COMPRESSES WITH CAM RISE

COEFFICIENT OF FRICTION: 0.020

START ANGLE	END ANGLE	START OFFSET	END OFFSET	SYMMETRY FACTOR	MOTION TYPE
0.0deg	180.0deg	2.0000in	6.0000in	1.000	Harmonic
180.0deg	360.0deg	6.0000in	2.0000in	1.000	Harmonic

CAM ROTATION APLHA	FOLLOWER POSITION BETA	VELOCITY wf	ACCELER- ATION wf2	PRESSURE ANGLE PHI	TORQUE T	NORMAL FORCE Pn	RADIUS OF CURVATURE Rc	CONTACT STRESS Sc	PULSE p
0.0	2.0000	0.00	79.0	0.0	0.0	12.0	1.002	28995.1	0.0
1.0	2.0003	0.22	78.9	1.0	0.4	12.0	1.002	28991.9	-8.7
2.0	2.0012	0.44	78.9	2.0	0.8	12.0	1.007	28872.8	-17.3
3.0	2.0027	0.66	78.8	3.0	1.3	12.0	1.016	28675.7	-26.0
4.0	2.0049	0.88	78.8	4.0	1.7	12.1	1.028	28408.6	-34.6
5.0	2.0076	1.10	78.7	5.0	2.1	12.1	1.044	28081.4	-43.2
6.0	2.0110	1.31	78.5	5.9	2.5	12.1	1.065	27705.7	-51.9
7.0	2.0149	1.53	78.4	6.9	2.9	12.1	1.089	27293.3	-60.5
8.0	2.0195	1.75	78.2	7.8	3.3	12.1	1.117	26855.6	-69.0
9.0	2.0246	1.97	78.0	8.8	3.7	12.1	1.150	26403.3	-77.6

Sample of a Data Sheet (Text Format)

Segment Configuration

Configure

beta	180.00000deg
h	4.00000in
h1	1.33333in
h2	2.66667in
n	2.00000
theta_1	60.00000deg
theta_2	120.00000deg

Maximum Velocity and Accelerations

Max_Negative_Acceleration	0.00in/sec^2
Max_Positive_Acceleration	0.00in/sec^2
Max_Velocity	0.00in/sec

Truncation

End_Truncation_by_Angle	0.00000deg
Start_Truncation_by_Angle	0.00000deg

n
theta 1-2 relationship

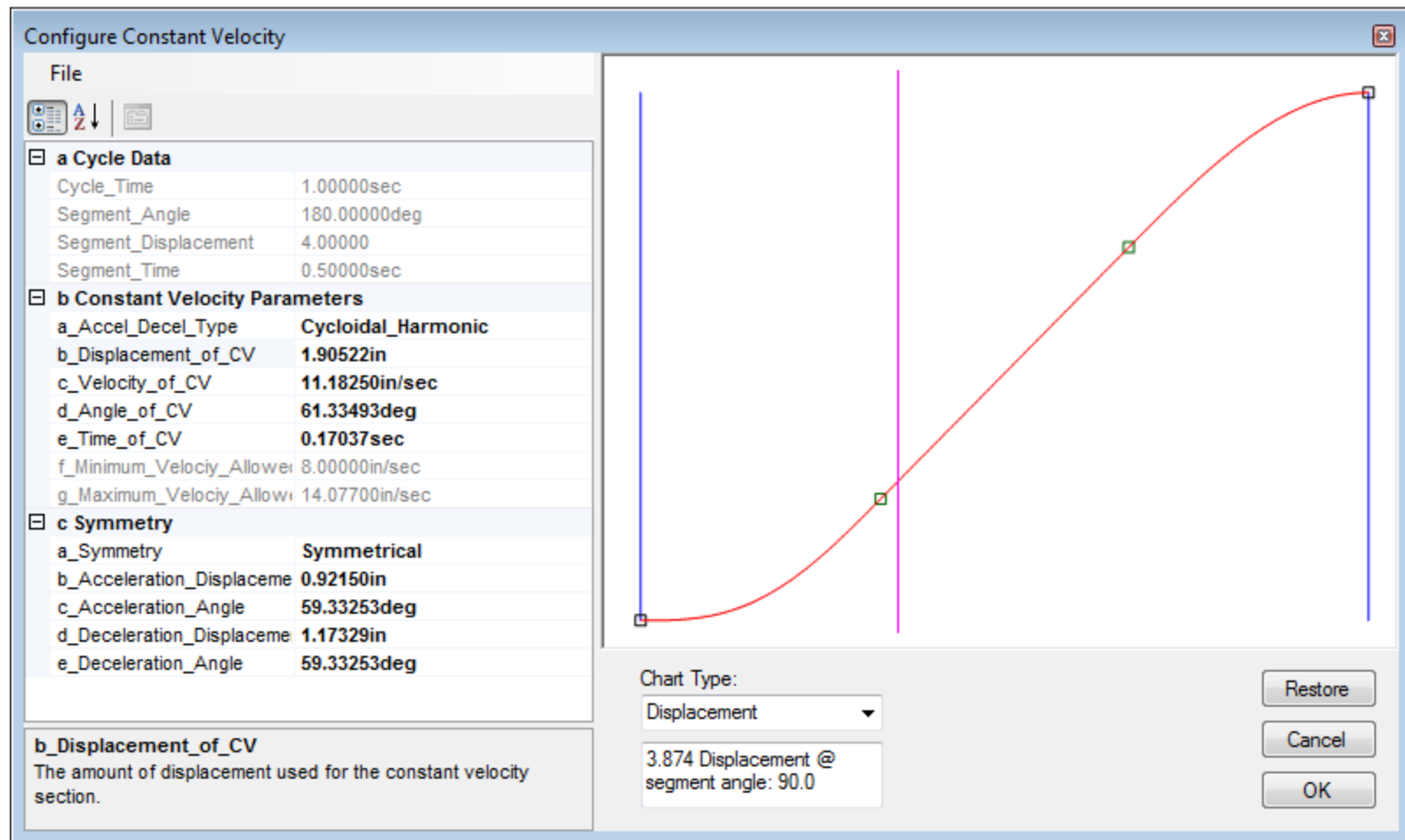
Print

Cancel

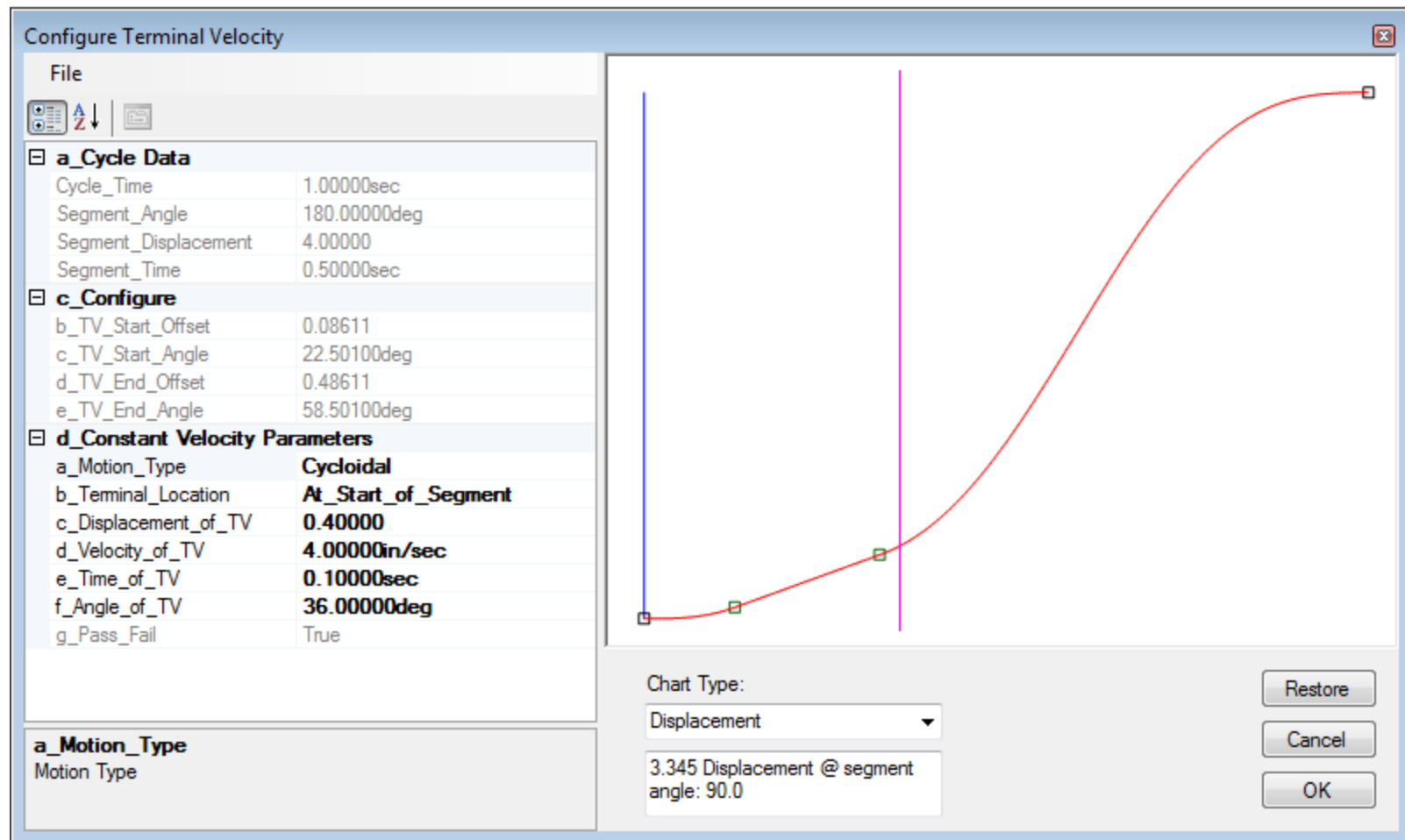
Apply

OK

Segment Configuration



Configure Constant Velocity



Configure Terminal Velocity

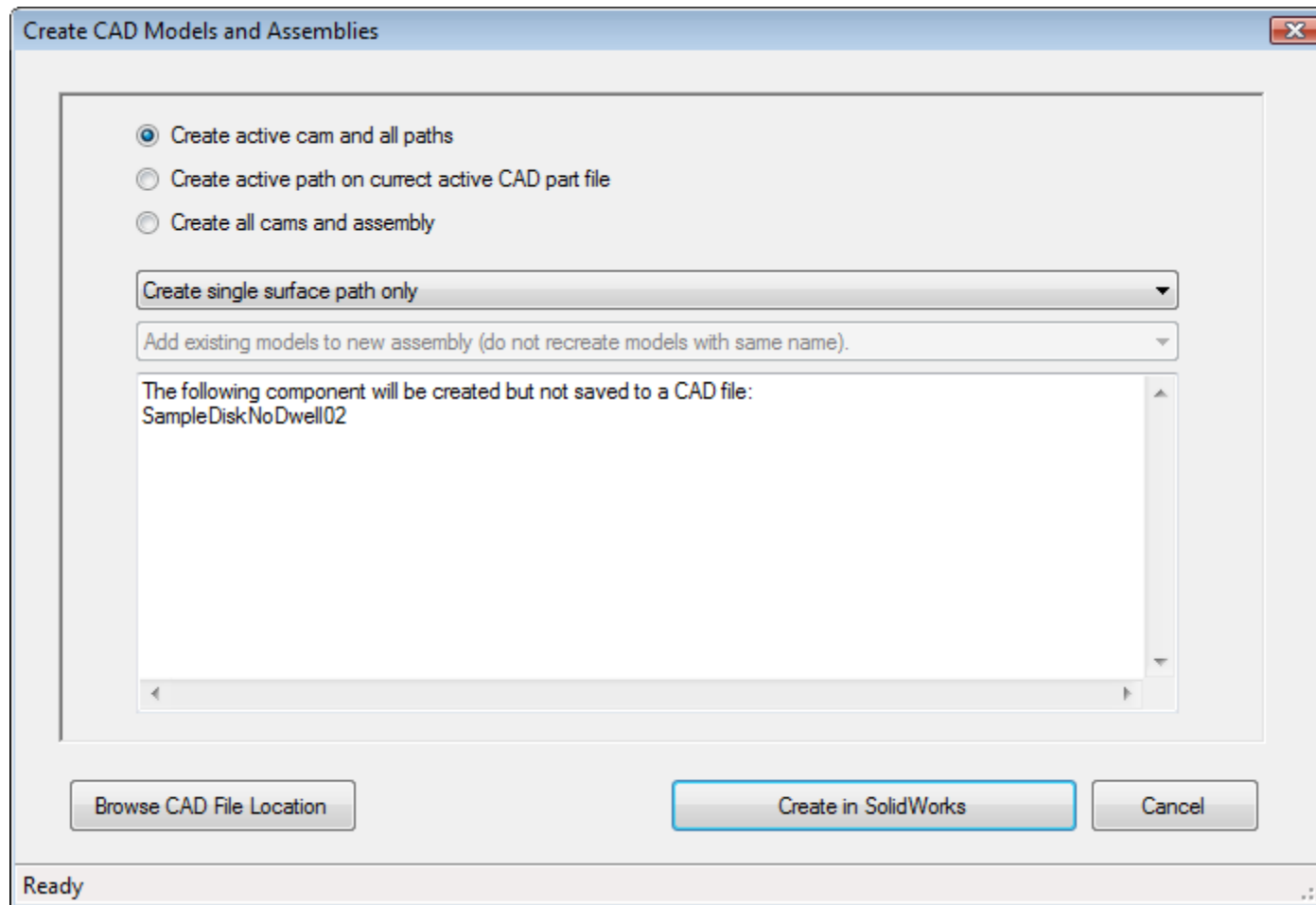
Configure User Points

0	5
1	5
2	4.9999
3	4.9995
4	4.9988
5	4.9978
6	4.9961
7	4.9939
8	4.9909
9	4.9871
10	4.9824
11	4.9767
12	4.9699
13	4.9619
14	4.9528
15	4.9423
16	4.9305
17	4.9174
18	4.9027
19	4.8866

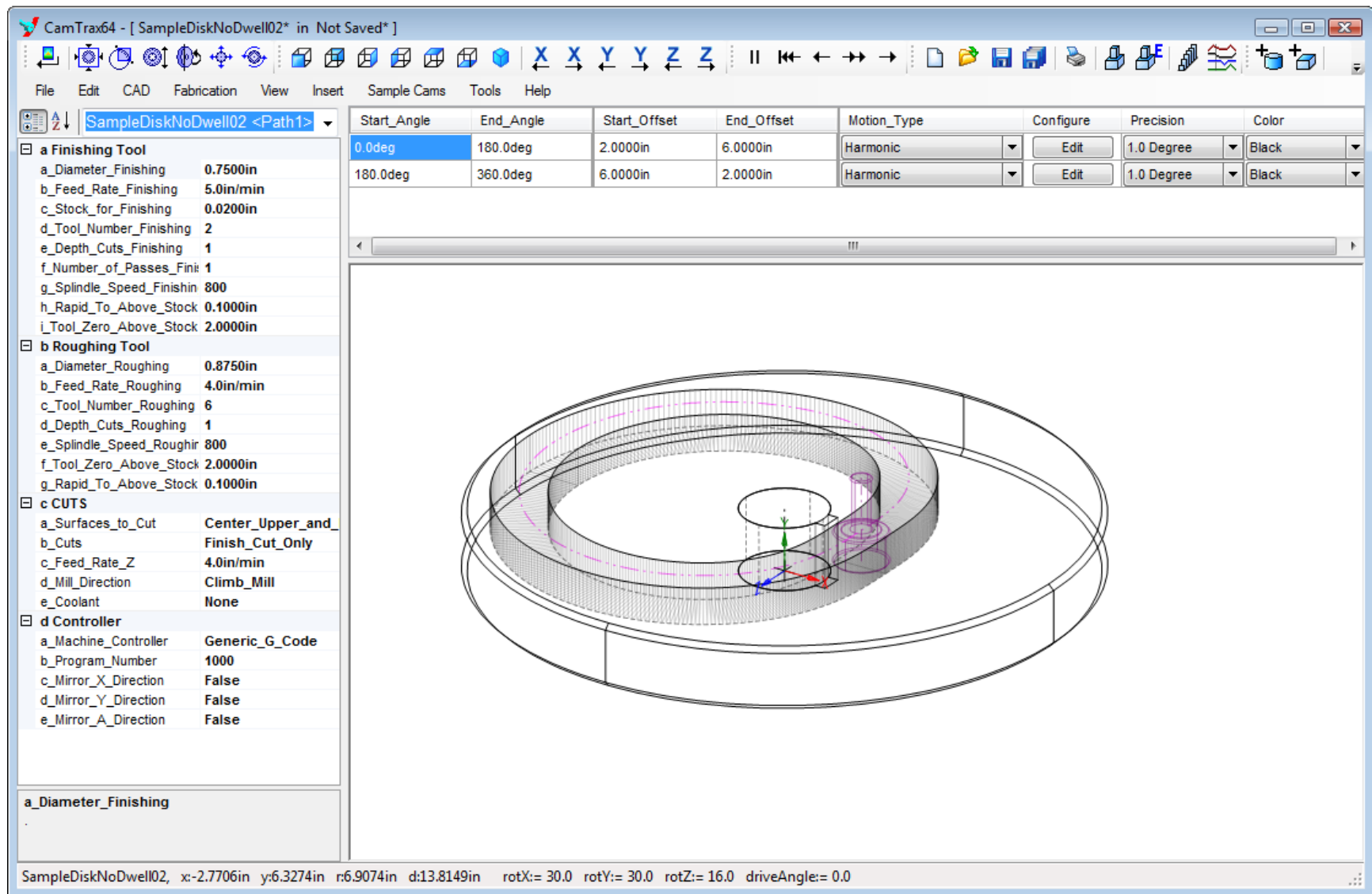
Copy and paste a single row of offset points or a double row of angle and offset points.
The cam beta for this segment is 90 at a precision increment of 1deg
91 points are required.

Apply Cancel OK

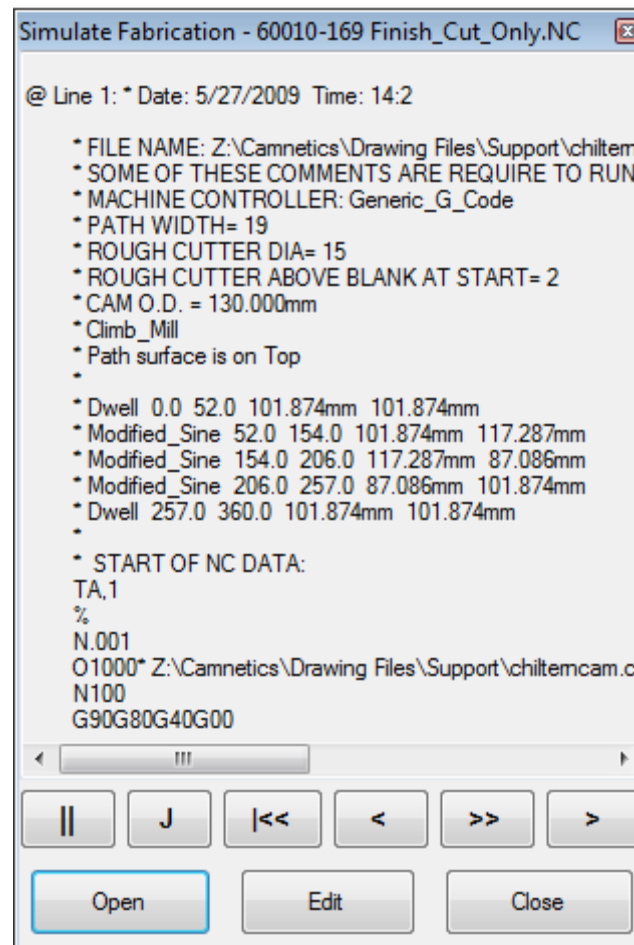
Configure User Points



Create CAD Models and Assemblies



Fabrication Properties



Simulate Fabrication